



MEASUREMENT UNCERTAINTY IN PROCESS OF LINE SCALES CALIBRATING

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Abstract: The paper presents main characteristics of the device for calibration of line scales and measurement uncertainty evaluation by GUM and MCS method. As a part of research on the impact of measurement uncertainty the following was investigated: the position of laser light sources and optical components, minimizing Abbe's error (Bosse at al. 2007), the determination of the middle line of line scales, alignment of line scale and laser beam, straightness movement of table, pitch, roll and yaw angles, environmental conditions affect the laser wavelength and the geometry of device and the impact of losing focus while moving of table. Measurement uncertainty evaluation has been validated in comparison measurements EURAMET Key Comparison, EURAMET.L-K7 "Calibration of line scales"

Key words: measurement uncertainty, line scale, length

1. INTRODUCTION

The Laboratory for Precise Measurement of Length, which is at the same time the National Laboratory for Length (in text 'Laboratory') takes part in CIPM MRA comparisons of length standards, which include line scales as very important standards of length. Calibration of the line scales at the level of measurement uncertainties of the order of value $U = 0,1\mu\text{m}$, $k = 2$. $P = 95\%$ represents today still a world problem, although these levels of measurement uncertainties are necessary in the context of ensuring the traceability. So, the Laboratory started to design their own optoelectronic system for the calibration of line scales.

2. MEASUREMENT DEVICE FOR CALIBRATING OF LINE SCALES

The measuring range of the device is 800 mm and it is primarily intended for the calibration of line scales. The sighting process is done by means of a microscope with a digital CCD camera Olympus DP 70 with 12, 5 Megapixels. The microscope is fitted with lens of different magnification (10X, 20X, 50X). The lenses are selected in compliance with the object of measurement.

The measuring system used is the laser interferometer (Reinshaw ML 10). The basis of the Renishaw Laser Interferometer system is He-Ne Laser operating at a wavelength of $0,663\mu\text{m}$. Measurement device for calibrating of line scales is presented in Figure 1. In order to achieve order in the above-mentioned measurement uncertainties, it is necessary to use software in the process of detecting the line centre of the measuring scale in reference to requirement limits (Beers and Penzes, 1999) The software solution functions in such a way that all the pixels of a certain image are transmitted into a black&white combination and then the position of the line centre is calculated by arithmetic algorithms (Družovec at.al. 2009).

The software solution provides the exact position of the line centre in pixels. In order to convert the values in pixels into the length values, it is necessary to calibrate the pixels size, i.e. to find out the length value of every pixel.

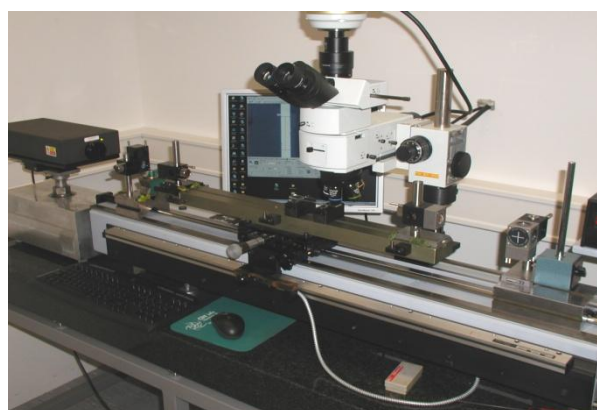


Fig. 1. Calibration system for precise measuring scales

3. CALCULATION OF THE MEASUREMENT UNCERTAINTY BY APPLYING GUM AND MCS METHOD

The mathematical model of measurement has been given by expression (1):

$$L_{MS} = (N_2 - N_1) \frac{\lambda}{2n_{air}} - (\delta l_{n2} - \delta l_{n1}) + \delta l_{DP} + \delta l_{li} + \delta l_{Az} + \delta l_{Ay} + L \cdot \alpha_s \cdot \Delta t_s + \delta l_{sh} + \delta l_{sv} + \delta l_{ai} + \delta E_{alg} + \delta e_{fok} + \delta l_{opt} + \delta l_{sE} \quad (1)$$

where:

- N_i - Number of wavelengths
- λ - Laser wavelength
- n_{air} - Refractive index of air
- δl_{ni} - Interferometer nonlinearity
- δl_{DP} - Deadpath influence
- δl_{li} - Interferometer cosine error
- δl_{Az} - Abbe offset in z and pitch
- δl_{Ay} - Abbe offset in y and yaw
- L - Nominal length of line scale
- α_s - Thermal exp. Coefficient
- Δt_s - Deviation scale temperature from 20°C
- δl_{sh} - Scale alignment horizontally
- δl_{sv} - Scale alignment vertically
- δl_{ai} - Scale support influence
- δE_{alg} - Line quality influence
- δe_{fok} - Focus loosing influence
- δl_{opt} - Uncertainty of measurement optics due to temp. dev.
- δl_{sE} - Reproducibility of line detection

The yields of components of the standard uncertainty for the line scale of 100 mm are presented in Table 1.

Source and Component of Uncertainty, x_i	Distr.	Amount of Stand. uncertainty $y u(x_i)$	$c_i = \partial dL / \partial x_i$	Yield to measure. uncertainty, nm, L in mm
Abbe offset in z and pitch, δLAz	R	16,8 nm	1	16,8
Abbe offset in y and yaw, δLAy	R	4,3 nm	1	4,3
Laser wavelength, $\delta \lambda$	R	0,03	L	0,03L
Air temperature, t_{air}	R	0,12 °C	$9,5 \cdot 10^{-7} L/°C$	0,112·L
Air pressure, p_{air}	R	13 Pa	$2,7 \cdot 10^{-7} L/Pa$	0,035·L
Relative humidity, RH_{air}	R	0,06	$8,5 \cdot 10^{-7} L$	0,050·L
Edlen equation uncertainty, δn_{air}	N	$2 \cdot 10^{-8}$	L	0,020·L
Deadpath, δIDP	R	1,8 nm	1	1,8
Interferometer nonlinearity, δINL	U	3 nm	1	3
Interferometer cosine error, δl_i	R	0,48L	1	0,48·L
Deviation scale temperature from 20 °C, Δt_s	N	0,12 °C	$5 \cdot 10^{-7} L/K$	0,06·L
Thermal exp. Coef., α_s , K^{-1}	R	$0,289 \cdot 10^{-7}$	L·0,5 K	0,0145·L
Scale alignment hor., δlSh	R	0,001L	1	0,001·L
Scale alignment vert., δlSV	R	0,0023L	1	0,0023·L
Scale support, δlai	R	0,0058L	1	0,0058·L
Line quality, $\delta Ealg$	N	6,4 nm	1	6,4
Focus loosing, $\delta efok$	N	18 nm	1	18
Measurement optics, $\delta lopt$	R	58 nm	1	58
Interferometer resolution, N	R	0,003	$\lambda/2$	1
Reproducibility of line detection, δlSE	N	11,6 nm	1	11,6
Combined variance			$u^2 = (65^2 + 0,5^2 \cdot L^2)$ nm, L in mm	
Linearised expanded measurement uncertainty U, $P = 95\%$, $k = 2$			$U = (130 + 0,66 \cdot L)$ nm, L in mm	

Tab. 1. Yields of components of standard uncertainty, and sources of uncertainty

Calculation of the measurement uncertainty (validation) has also been performed, by means of MCS method (JCGM 101:2008.) Probability density function of the output value has been obtained by $M = 100000$ simulations. The probability density function $g(x_i)$ has been simulated by the MCS method based on the expression (1). Figures 2 and 3 show the probability density functions of the output value L_{MS} where the distance between spots of reference and reflected beams are $s = 2$ mm and $s = 5$ mm respectively.

While the GUM method assumes normal distribution of the output value, the MCS method yielded experimental distribution of the output value that may more or less match the assumed normal distribution. The form of the experimental curve will depend primarily on the probability density function of the most significant input value (Medic et al., 2003).

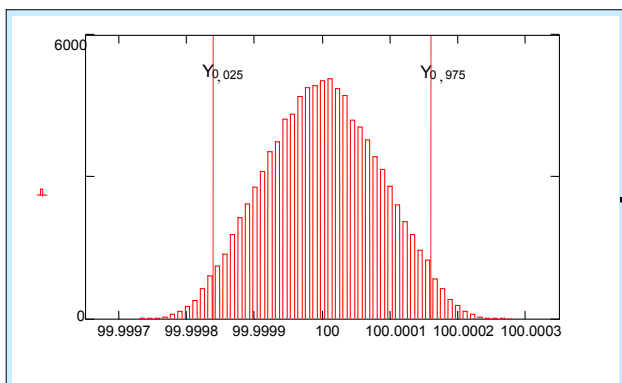


Fig. 2. Probability density function $g(L_{MS})$ where $s = 2$ mm

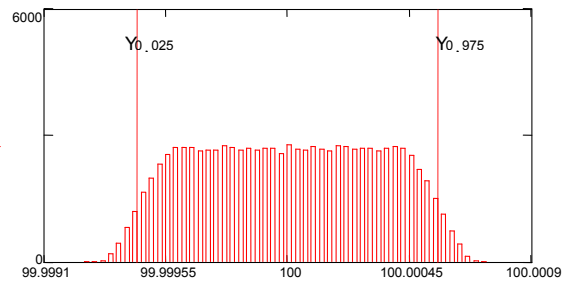


Fig. 3. Probability density function $g(L_{MS})$ where $s = 5$ mm

In this case, due to the dominant influence of interferometer cosine error (Quenelle, 1983.) on the measurement uncertainty, the normal distribution assumes, through length increase, the characteristics of a trapezoid distribution (Fig. 3).

4. CONCLUSION

By designing the measurement system for calibration of precise line scales, the Laboratory has opened the possibility of carrying out the international comparisons in the field of line scales. Thus, the Laboratory participated in the EUROMET project 882 "Calibration of line scales", L-K7. Intercomparison results of measuring the length of the 100 mm line scale are presented in Figure 4. Figure 4 shows that obtained results of Laboratory have no significant deviation compared to average of results of METAS, PTB and MIKES and that they have the same trend.

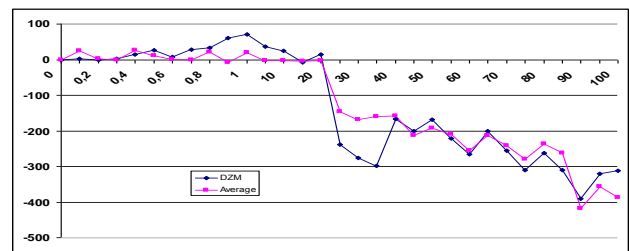


Fig. 4. Intercomparison results of measuring the length of the 100 mm line scale

The participation in this international comparison measurement was representing a real validation of the device and evaluated measurement uncertainty. The obtained results of this comparison will be good indication about direction of future research in a way to reduce measurement uncertainty in calibration of line scales.

6. REFERENCES

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